

# Two-phase optimal design for elastic plate



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DYNAMICAL SYSTEMS, DUBROVNIK]

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## Kirchhoff-Love plate equation

Homogeneous Dirichlet boundary value problem:

$$\begin{cases} \operatorname{div} \operatorname{div} (\mathbf{M} \nabla \nabla u) = f & \text{in } \Omega \\ u \in H_0^2(\Omega). \end{cases}$$

P. G. Ciarlet, *Mathematical Elasticity, volume II: Theory of Plates*, Elsevier Science, Amsterdam, 1997.

- $\Omega \subseteq \mathbb{R}^d$  bounded domain ( $d = 2 \dots$  plate)
- $f \in H^{-2}(\Omega)$  external load
- $u \in H_0^2(\Omega)$  vertical displacement of the plate
- $\mathbf{M} \in \mathfrak{M}_2(\alpha, \beta; \Omega) := \{ \mathbf{N} \in L^\infty(\Omega; \mathcal{L}(\operatorname{Sym}, \operatorname{Sym})) : (\forall \mathbf{S} \in \operatorname{Sym}) \mathbf{N}(\mathbf{x}) \mathbf{S} : \mathbf{S} \geq \alpha \mathbf{S} : \mathbf{S} \text{ and } \mathbf{N}^{-1}(\mathbf{x}) \mathbf{S} : \mathbf{S} \geq \frac{1}{\beta} \mathbf{S} : \mathbf{S} \text{ a.e. } \mathbf{x} \}$   
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Antonić, Balenović, 1999.

## Definition

A sequence of tensor functions  $(\mathbf{M}^n)$  in  $\mathfrak{M}_2(\alpha, \beta; \Omega)$  H-converges to  $\mathbf{M} \in \mathfrak{M}_2(\alpha', \beta'; \Omega)$  if for any  $f \in H^{-2}(\Omega)$  the sequence of solutions  $(u_n)$  of problems

$$\begin{cases} \operatorname{div} \operatorname{div} (\mathbf{M}^n \nabla \nabla u_n) = f & \text{in } \Omega \\ u_n \in H_0^2(\Omega) \end{cases}$$

converges weakly to a limit  $u$  in  $H_0^2(\Omega)$ , while the sequence  $(\mathbf{M}^n \nabla \nabla u_n)$  converges to  $\mathbf{M} \nabla \nabla u$  weakly in the space  $L^2(\Omega; \operatorname{Sym})$ .

## Theorem

*Let  $(\mathbf{M}^n)$  be a sequence in  $\mathfrak{M}_2(\alpha, \beta; \Omega)$ . Then there is a subsequence  $(\mathbf{M}^{n_k})$  and a tensor function  $\mathbf{M} \in \mathfrak{M}_2(\alpha, \beta; \Omega)$  such that  $(\mathbf{M}^{n_k})$  H-converges to  $\mathbf{M}$ .*



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## Properties

K. Burazin, J. Jankov, M. Vrdoljak, *Homogenization of elastic plate equation*, *Mathematical Modelling and Analysis* 23(2), 190-204, 2018.

- Locality of the H-convergence
- Irrelevance of boundary conditions
- Energy convergence
- Ordering property
- Metrizability
- Corrector results



## Definition

Let  $\chi^n \in L^\infty(\Omega; \{0, 1\})$  be a sequence of characteristic functions and  $(\mathbf{M}^n)$  be a sequence of tensors defined by

$$\mathbf{M}^n(\mathbf{x}) = \chi^n(\mathbf{x})\mathbf{A} + (1 - \chi^n(\mathbf{x}))\mathbf{B},$$

where  $\mathbf{A}$  and  $\mathbf{B}$  are assumed to be positive definite fourth order tensors. Assume that there exist  $\theta \in L^\infty(\Omega; [0, 1])$  and  $\mathbf{M} \in L^\infty(\Omega; \mathcal{L}(\text{Sym}, \text{Sym}))$  such that

$$\chi^n \xrightarrow{*} \theta \text{ in } L^\infty(\Omega; [0, 1]),$$

$$\mathbf{M}^n \xrightarrow{H} \mathbf{M} \text{ in } \mathfrak{M}_2(\alpha, \beta; \Omega).$$

The  $H$ -limit  $\mathbf{M}$  is said to be the homogenized tensor of a two-phase composite material obtained by mixing  $\mathbf{A}$  and  $\mathbf{B}$  in proportions  $\theta$  and  $(1 - \theta)$ , respectively, with a microstructure defined by the sequence  $(\chi^n)$ .



$\Omega$  - mixture of two isotropic elastic phases with stiffness tensors

$$\mathbf{A} = 2\mu_1 \mathbf{I}_4 + (\kappa_1 - \mu_1) \mathbf{I}_2 \otimes \mathbf{I}_2$$

$$\mathbf{B} = 2\mu_2 \mathbf{I}_4 + (\kappa_2 - \mu_2) \mathbf{I}_2 \otimes \mathbf{I}_2$$

$$0 < \mu_1 \leq \mu_2, 0 < \kappa_1 \leq \kappa_2$$

$$\mathbf{M}(\mathbf{x}) = \chi(\mathbf{x})\mathbf{A} + (1 - \chi(\mathbf{x}))\mathbf{B}, \quad \chi \in L^\infty(\Omega; \{0, 1\})$$





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## Optimal design problem

$$\begin{cases} J(\chi) = \int_{\Omega} [\chi(\mathbf{x})g_1(\mathbf{x}, u(\mathbf{x})) + (1 - \chi(\mathbf{x}))g_2(\mathbf{x}, u(\mathbf{x}))] d\mathbf{x} \longrightarrow \min, \\ \chi \in L^{\infty}(\Omega; \{0, 1\}), \int_{\Omega} \chi d\mathbf{x} = q. \end{cases}$$

$0 < q < |\Omega|$ , and  $g_1, g_2$  Caratheodory functions which satisfy growth condition

$$g_{1,2}(\mathbf{x}, u) \leq a|u|^s + b(\mathbf{x}),$$

for some  $a > 0, b \in L^1(\Omega)$  and  $1 \leq s < \frac{2d}{d-2}$ , and  $u$  is the solution of

$$\begin{cases} \operatorname{div} \operatorname{div} (\mathbf{M} \nabla \nabla u) = f & \text{in } \Omega \\ u \in H_0^2(\Omega), \end{cases}$$

where  $f \in H^{-2}(\Omega)$ ,  $\mathbf{M}(\mathbf{x}) = \chi(\mathbf{x})\mathbf{A} + (1 - \chi(\mathbf{x}))\mathbf{B}$ .



$$\begin{cases} J(\theta, \mathbf{M}) := \int_{\Omega} [\theta(\mathbf{x})g_1(\mathbf{x}, u(\mathbf{x})) + (1 - \theta)(\mathbf{x})g_2(\mathbf{x}, u(\mathbf{x}))] dx + l \int_{\Omega} \theta(\mathbf{x}) dx \longrightarrow \min, \\ (\theta, \mathbf{M}) \in L^{\infty}(\Omega; [0, 1] \times \mathcal{L}(\text{Sym}, \text{Sym})); \mathbf{M}(\mathbf{x}) \in G_{\theta(\mathbf{x})} \text{ a.e. on } \Omega. \end{cases} \quad (3.1)$$

Set of all composites:

$$\mathcal{A} := \{(\theta, \mathbf{M}) \in L^{\infty}(\Omega; [0, 1] \times \mathcal{L}(\text{Sym}, \text{Sym})) : \mathbf{M}(\mathbf{x}) \in G_{\theta(\mathbf{x})} \text{ a.e. on } \Omega\}$$

**G-closure problem:** for given  $\theta$  find all possible homogenized (effective) tensors  $\mathbf{M}$  - open problem

For  $g_1 = g_2 = fu$ , it follows

$$J(\theta, \mathbf{M}) = \int_{\Omega} f(\mathbf{x})u(\mathbf{x}) dx + l \int_{\Omega} \theta(\mathbf{x}) dx.$$



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## Homogenization of laminated structures

### Theorem

Let  $\mathbf{A}$  and  $\mathbf{B}$  be two constant tensors in  $\mathfrak{M}_2(\alpha, \beta; \Omega)$  and  $\chi_n(\mathbf{x} \cdot \mathbf{e})$  be a sequence of characteristic functions that converges to  $\theta(\mathbf{x} \cdot \mathbf{e})$  in  $L^\infty(\Omega; [0, 1])$  weakly-\*. Then, sequence  $(\mathbf{M}^n)$  of tensors in  $\mathfrak{M}_2(\alpha, \beta; \Omega)$ , defined as

$$\mathbf{M}^n(\mathbf{x} \cdot \mathbf{e}) = \chi_n(\mathbf{x} \cdot \mathbf{e})\mathbf{A} + (1 - \chi_n(\mathbf{x} \cdot \mathbf{e}))\mathbf{B}$$

*H*-converges to

$$\mathbf{M} = \theta\mathbf{A} + (1 - \theta)\mathbf{B} - \frac{\theta(1 - \theta)(\mathbf{A} - \mathbf{B})(\mathbf{e} \otimes \mathbf{e}) \otimes (\mathbf{A} - \mathbf{B})^T(\mathbf{e} \otimes \mathbf{e})}{(1 - \theta)\mathbf{A}(\mathbf{e} \otimes \mathbf{e}) : (\mathbf{e} \otimes \mathbf{e}) + \theta\mathbf{B}(\mathbf{e} \otimes \mathbf{e}) : (\mathbf{e} \otimes \mathbf{e})}, \quad (3.2)$$

which also depends only on  $\mathbf{x} \cdot \mathbf{e}$ .



## Corollary

If  $(\mathbf{A} - \mathbf{B})$  is an invertible fourth order tensor, formula (3.2) is equivalent to

$$\theta(\mathbf{M} - \mathbf{B})^{-1} = (\mathbf{A} - \mathbf{B})^{-1} + \frac{1 - \theta}{\mathbf{B}(\mathbf{e} \otimes \mathbf{e}) : (\mathbf{e} \otimes \mathbf{e})} (\mathbf{e} \otimes \mathbf{e}) \otimes (\mathbf{e} \otimes \mathbf{e}). \quad (3.3)$$

If we repeat iterative process of lamination  $p$  times, in lamination directions  $(\mathbf{e}_i)_{1 \leq i \leq p}$  and proportions  $(\theta_i)_{1 \leq i \leq p}$ , we obtain a rank- $p$  sequential laminate with matrix  $\mathbf{B}$  and core  $\mathbf{A}$ , which is defined by the following formula:

$$\left( \prod_{j=1}^p \theta_j \right) (\mathbf{A}_p^* - \mathbf{B})^{-1} = (\mathbf{A} - \mathbf{B})^{-1} + \sum_{i=1}^p \left( (1 - \theta_i) \prod_{j=1}^{i-1} \theta_j \right) \frac{(\mathbf{e}_i \otimes \mathbf{e}_i) \otimes (\mathbf{e}_i \otimes \mathbf{e}_i)}{\mathbf{B}(\mathbf{e}_i \otimes \mathbf{e}_i) : (\mathbf{e}_i \otimes \mathbf{e}_i)}.$$

$$\theta(\mathbf{M}^{-1} - \mathbf{B}^{-1})^{-1} = (\mathbf{A}^{-1} - \mathbf{B}^{-1})^{-1} + (1 - \theta) \left[ \mathbf{B} - \mathbf{B} \frac{(\mathbf{e} \otimes \mathbf{e}) \otimes (\mathbf{e} \otimes \mathbf{e})}{\mathbf{B}(\mathbf{e} \otimes \mathbf{e}) : (\mathbf{e} \otimes \mathbf{e})} \mathbf{B} \right]$$



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## Lemma

Let  $\theta$  be a volume fraction in  $[0, 1]$ ,  $(\mathbf{e}_i)_{1 \leq i \leq p}$  unit vectors in  $\mathbf{R}^d$ , and  $(m_i)_{1 \leq i \leq p}$  nonnegative real numbers such that  $\sum_{i=1}^p m_i = 1$ . Then, there exists a rank- $p$  sequential laminate  $\mathbf{A}_p^*$  with core  $\mathbf{A}$  and matrix  $\mathbf{B}$ , and with lamination directions  $\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_p$ , such that

$$\theta(\mathbf{A}_p^{*-1} - \mathbf{B}^{-1})^{-1} = (\mathbf{A}^{-1} - \mathbf{B}^{-1})^{-1} + (1 - \theta) \left[ \mathbf{B} - \sum_{i=1}^p m_i \mathbf{B} \frac{(\mathbf{e}_i \otimes \mathbf{e}_i) \otimes (\mathbf{e}_i \otimes \mathbf{e}_i)}{\mathbf{B}(\mathbf{e}_i \otimes \mathbf{e}_i) : (\mathbf{e}_i \otimes \mathbf{e}_i)} \mathbf{B} \right]. \quad (3.4)$$

One could interchange the roles of  $\mathbf{A}$  and  $\mathbf{B}$  and obtain a symmetric class of sequential laminates:

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$$(1 - \theta)(\mathbf{A}_p^{*-1} - \mathbf{A}^{-1})^{-1} = (\mathbf{B}^{-1} - \mathbf{A}^{-1})^{-1} + \theta \left[ \mathbf{A} - \sum_{i=1}^p m_i \mathbf{A} \frac{(\mathbf{e}_i \otimes \mathbf{e}_i) \otimes (\mathbf{e}_i \otimes \mathbf{e}_i)}{\mathbf{A}(\mathbf{e}_i \otimes \mathbf{e}_i) : (\mathbf{e}_i \otimes \mathbf{e}_i)} \mathbf{A} \right]. \quad (3.5)$$



## Theorem

The homogenized tensor  $\mathbf{A}^* \in G_\theta$  satisfies

$$(\forall \boldsymbol{\sigma} \in \text{Sym}) \quad \mathbf{A}^{*-1} \boldsymbol{\sigma} : \boldsymbol{\sigma} \geq \mathbf{B}^{-1} \boldsymbol{\sigma} : \boldsymbol{\sigma} + \theta \max_{\boldsymbol{\eta} \in \text{Sym}} [2\boldsymbol{\sigma} : \boldsymbol{\eta} - (\mathbf{A}^{-1} - \mathbf{B}^{-1})^{-1} \boldsymbol{\eta} : \boldsymbol{\eta} - (1 - \theta)g^c(\boldsymbol{\eta})], \quad (3.6)$$

where

$$g^c(\boldsymbol{\eta}) := \mathbf{B}\boldsymbol{\eta} : \boldsymbol{\eta} - h_{\mathbf{B}}(\boldsymbol{\eta}), \quad (3.7)$$

while  $h_{\mathbf{B}}(\boldsymbol{\eta})$  is defined with

$$h_{\mathbf{B}}(\boldsymbol{\eta}) := \min_{\mathbf{e} \in S^{d-1}} \frac{|(\mathbf{e} \otimes \mathbf{e}) : \mathbf{B}\boldsymbol{\eta}|^2}{\mathbf{B}(\mathbf{e} \otimes \mathbf{e}) : (\mathbf{e} \otimes \mathbf{e})}. \quad (3.8)$$

Moreover,

$$(\forall \boldsymbol{\sigma} \in \text{Sym}) \quad \mathbf{A}^{*-1} \boldsymbol{\sigma} : \boldsymbol{\sigma} \leq \mathbf{A}^{-1} \boldsymbol{\sigma} : \boldsymbol{\sigma} + (1 - \theta) \min_{\boldsymbol{\eta} \in \text{Sym}} [2\boldsymbol{\sigma} : \boldsymbol{\eta} + (\mathbf{A}^{-1} - \mathbf{B}^{-1})^{-1} \boldsymbol{\eta} : \boldsymbol{\eta} - \theta h^c(\boldsymbol{\eta})], \quad (3.9)$$

where

$$h^c(\boldsymbol{\eta}) := \mathbf{A}\boldsymbol{\eta} : \boldsymbol{\eta} - g_{\mathbf{A}}(\boldsymbol{\eta}), \quad (3.10)$$

while  $g_{\mathbf{A}}(\boldsymbol{\eta})$  is defined with

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Additionally, (3.6) and (3.9) are optimal and optimality is achieved by a rank- $p$  sequential laminate,

where  $p = \frac{(d+3)(d+2)(d+1)d}{24} + 1$ .



### Theorem

After denoting by  $\sigma_1$  and  $\sigma_2$  the eigenvalues of  $\sigma$ , and  $\theta_1 := \theta$ ,  $\theta_2 := 1 - \theta$  as before, the explicit formula for the bound (3.6) is given as follows:

(i) If

$$\begin{aligned} \theta_2 \mu_2 (\kappa_2 - \kappa_1) |\sigma_1 + \sigma_2| &< (\theta_1 \mu_2 \kappa_1 + \theta_2 \mu_2 \kappa_2 + \kappa_1 \kappa_2) |\sigma_1 - \sigma_2| \quad \& \quad (3.12) \\ (\kappa_2 - \kappa_1) (\theta_1 \mu_1 + \theta_2 \mu_2) |\sigma_1 + \sigma_2| &\geq (\mu_2 - \mu_1) (\theta_1 \kappa_1 + \theta_2 \kappa_2) |\sigma_1 - \sigma_2|, \end{aligned}$$

then

$$\begin{aligned} \mathbf{A}^{*-1} \sigma : \sigma &\geq (\theta_1 \mathbf{A}^{-1} + \theta_2 \mathbf{B}^{-1}) \sigma : \sigma - \\ &- \theta_1 \theta_2 \frac{[\mu_1 \mu_2 (\kappa_2 - \kappa_1) |\sigma_1 + \sigma_2| + \kappa_1 \kappa_2 (\mu_2 - \mu_1) |\sigma_1 - \sigma_2|]^2}{4 \mu_1 \mu_2 \kappa_1 \kappa_2 [\mu_1 \kappa_1 \theta_1 (\mu_2 + \kappa_2) + \mu_2 \kappa_2 \theta_2 (\kappa_1 + \mu_1)]}. \end{aligned}$$

In this case the optimal microstructure for which the bound is saturated is a simple laminate with layers orthogonal to the eigenvector associated with an eigenvalue of the least absolute value, of the extremal  $\eta$  in (3.6).

(ii) If

$$(\kappa_2 - \kappa_1) (\theta_1 \mu_1 + \theta_2 \mu_2) |\sigma_1 + \sigma_2| < (\mu_2 - \mu_1) (\theta_1 \kappa_1 + \theta_2 \kappa_2) |\sigma_1 - \sigma_2|, \quad (3.13)$$

then

$$\mathbf{A}^{*-1} \sigma : \sigma \geq \mathbf{B}^{-1} \sigma : \sigma + \frac{\theta_1}{4} \left[ \frac{(\mu_2 - \mu_1) (\sigma_1 - \sigma_2)^2}{\mu_2 (\theta_1 \mu_1 + \theta_2 \mu_2)} + \frac{(\kappa_2 - \kappa_1) (\sigma_1 + \sigma_2)^2}{\kappa_2 (\theta_1 \kappa_1 + \theta_2 \kappa_2)} \right].$$

The optimal microstructure for which this bound is saturated is a simple laminate with layers orthogonal to  $\mathbf{e}$ , such that  $\mathbf{e}$  is an extremal for

$$h_{\mathbf{B}}(\eta) = \min_{\mathbf{e} \in S^1} \frac{|(\mathbf{e} \otimes \mathbf{e}) : \mathbf{B}\eta|^2}{\mathbf{B}(\mathbf{e} \otimes \mathbf{e}) : (\mathbf{e} \otimes \mathbf{e})}, \quad (3.14)$$

where  $h_{\mathbf{B}}$  is function of extremal  $\eta$  in (3.6).



## Theorem

(iii) If

$$\mu_2\theta_2(\kappa_2 - \kappa_1)|\sigma_1 + \sigma_2| \geq (\theta_1\mu_2\kappa_1 + \theta_2\mu_2\kappa_2 + \kappa_1\kappa_2)|\sigma_1 - \sigma_2|, \quad (3.15)$$

then

$$\mathbf{A}^{*-1}\boldsymbol{\sigma} : \boldsymbol{\sigma} \geq \mathbf{B}^{-1}\boldsymbol{\sigma} : \boldsymbol{\sigma} + \frac{\theta_1(\kappa_2 - \kappa_1)(\mu_2 + \kappa_2)(\sigma_1 + \sigma_2)^2}{4\kappa_2[\kappa_1(\mu_2 + \kappa_2) + \mu_2(\kappa_2 - \kappa_1)\theta_2]}.$$

In this case, the optimal microstructure for which the bound is saturated is a rank-2 laminate with directions of lamination given by eigenvectors  $\mathbf{v}_1$  and  $\mathbf{v}_2$  of  $\boldsymbol{\sigma}$ , and corresponding lamination parameters

$$m_1 = \frac{2\theta_2\mu_2(\kappa_1 - \kappa_2)\sigma_2 + \kappa_1(\mu_2 + \kappa_2)(\sigma_1 - \sigma_2)}{2\theta_2\mu_2(\kappa_1 - \kappa_2)(\sigma_1 + \sigma_2)},$$

$$m_2 = \frac{2\theta_2\mu_2(\kappa_1 - \kappa_2)\sigma_1 - \kappa_1(\mu_2 + \kappa_2)(\sigma_1 - \sigma_2)}{2\theta_2\mu_2(\kappa_1 - \kappa_2)(\sigma_1 + \sigma_2)}.$$

Cases (i) – (iii) are disjoint, and the union of all  $(\sigma_1, \sigma_2) \in \mathbf{R}^2$  which satisfy one of the conditions (3.12), (3.13) and (3.15), equals  $\mathbf{R}^2$ .



### Theorem

After denoting by  $\sigma_1$  and  $\sigma_2$  the eigenvalues of  $\sigma$ , and  $\theta_1 := \theta$ ,  $\theta_2 := 1 - \theta$  as before, the explicit formula for the bound (3.9) is given as follows:

(i) If

$$\begin{aligned} \theta_1 \mu_1 (\kappa_2 - \kappa_1) |\sigma_1 + \sigma_2| &< (\theta_2 \mu_1 \kappa_2 + \theta_1 \mu_1 \kappa_1 + \kappa_1 \kappa_2) |\sigma_2 - \sigma_1| \quad \& \quad (3.16) \\ \theta_1 \kappa_1 (\mu_2 - \mu_1) |\sigma_2 - \sigma_1| &< (\theta_1 \mu_1 \kappa_1 + \theta_2 \mu_2 \kappa_1 + \mu_1 \mu_2) |\sigma_1 + \sigma_2|, \end{aligned}$$

then

$$\begin{aligned} \mathbf{A}^{*-1} \sigma : \sigma \leq (\theta_1 \mathbf{A}^{-1} + \theta_2 \mathbf{B}^{-1}) \sigma : \sigma - \\ - \theta_1 \theta_2 \frac{[\mu_1 \mu_2 (\kappa_1 - \kappa_2) |\sigma_1 + \sigma_2| + \kappa_1 \kappa_2 (\mu_2 - \mu_1) |\sigma_1 - \sigma_2|]^2}{4 \mu_1 \mu_2 \kappa_1 \kappa_2 [\mu_1 \kappa_1 \theta_1 (\mu_2 + \kappa_2) + \mu_2 \kappa_2 \theta_2 (\kappa_1 + \mu_1)]}. \end{aligned}$$

In this case the optimal microstructure for which the bound is saturated is a simple laminate with layers orthogonal to the eigenvector associated with an eigenvalue of the largest absolute value, of the extremal  $\eta$  in (3.9).

(ii) If

$$\theta_1 \mu_1 (\kappa_2 - \kappa_1) |\sigma_1 + \sigma_2| \geq (\theta_2 \mu_1 \kappa_2 + \theta_1 \mu_1 \kappa_1 + \kappa_1 \kappa_2) |\sigma_2 - \sigma_1|, \quad (3.17)$$

then

$$\mathbf{A}^{*-1} \sigma : \sigma \leq \mathbf{A}^{-1} \sigma : \sigma + \frac{\theta_2 (\mu_1 + \kappa_1) (\kappa_1 - \kappa_2) (\sigma_1 + \sigma_2)^2}{4 \kappa_1 [\kappa_2 (\mu_1 + \kappa_1) + \theta_1 \mu_1 (\kappa_1 - \kappa_2)]}.$$

The optimal microstructure for which the bound (3.9) is saturated is a rank-2 laminate with directions of lamination given by eigenvectors  $\mathbf{v}_1$  and  $\mathbf{v}_2$  of  $\sigma$ , and corresponding lamination parameters

$$\begin{aligned} m_1 &= \frac{2\theta_1 \mu_1 (\kappa_2 - \kappa_1) \sigma_2 + \kappa_2 (\mu_1 + \kappa_1) (\sigma_1 - \sigma_2)}{2\theta_1 \mu_1 (\kappa_2 - \kappa_1) (\sigma_1 + \sigma_2)}, \\ m_2 &= \frac{2\theta_1 \mu_1 (\kappa_2 - \kappa_1) \sigma_1 + \kappa_2 (\mu_1 + \kappa_1) (\sigma_2 - \sigma_1)}{2\theta_1 \mu_1 (\kappa_2 - \kappa_1) (\sigma_1 + \sigma_2)}. \end{aligned}$$



## Theorem

(iii) If

$$\theta_1 \kappa_1 (\mu_2 - \mu_1) |\sigma_2 - \sigma_1| \geq (\theta_1 \mu_1 \kappa_1 + \theta_2 \mu_2 \kappa_1 + \mu_1 \mu_2) |\sigma_1 + \sigma_2|, \quad (3.18)$$

then

$$\mathbf{A}^{*-1} \boldsymbol{\sigma} : \boldsymbol{\sigma} \leq \mathbf{A}^{-1} \boldsymbol{\sigma} : \boldsymbol{\sigma} + \frac{\theta_2 (\mu_1 - \mu_2) (\mu_1 + \kappa_1) (\sigma_1 - \sigma_2)^2}{4 \mu_1 [\mu_2 (\mu_1 + \kappa_1) + \theta_1 \kappa_1 (\mu_1 - \mu_2)]}.$$

In this case, the optimal microstructure for which the bound (3.9) is saturated is a rank-2 laminate with directions of lamination given with eigenvectors  $\mathbf{v}_1$  and  $\mathbf{v}_2$  of the extremal  $\boldsymbol{\eta}$  in (3.9) (which are also eigenvectors of  $\boldsymbol{\sigma}$ ), and corresponding lamination parameters

$$m_1 = \frac{2 \kappa_1 \theta_1 (\mu_2 - \mu_1) \sigma_2 - \mu_2 (\mu_1 + \kappa_1) (\sigma_1 + \sigma_2)}{2 \kappa_1 \theta_1 (\mu_2 - \mu_1) (\sigma_2 - \sigma_1)},$$

$$m_2 = \frac{-2 \kappa_1 \theta_1 (\mu_2 - \mu_1) \sigma_1 + \mu_2 (\mu_1 + \kappa_1) (\sigma_1 + \sigma_2)}{2 \kappa_1 \theta_1 (\mu_2 - \mu_1) (\sigma_2 - \sigma_1)}.$$

Cases (i) – (iii) are disjoint, and the union of all  $(\sigma_1, \sigma_2) \in \mathbf{R}^2$  which satisfy one of the conditions (3.16), (3.17) and (3.18), equals  $\mathbf{R}^2$ .





## Compliance minimization

For  $g_1 = g_2 = fu$ , it follows

$$J(\theta, \mathbf{M}) = \int_{\Omega} f(\mathbf{x})u(\mathbf{x}) d\mathbf{x} + l \int_{\Omega} \theta(\mathbf{x}) d\mathbf{x}. \quad (3.19)$$

By the principle of minimal complementary energy we have

$$\int_{\Omega} f(\mathbf{x})u(\mathbf{x}) = \min_{\substack{\tau \in L^2(\Omega; \text{Sym}) \\ \text{div div } \tau = f \text{ in } \Omega}} \int_{\Omega} \mathbf{M}^{-1} \tau : \tau d\mathbf{x},$$

and the minimum on the right hand side is achieved by  $\sigma = \mathbf{M} \nabla \nabla u$ .

Therefore, (2) can be rewritten as

$$J(\theta, \mathbf{M}) = \min_{\substack{\tau \in L^2(\Omega; \text{Sym}) \\ \text{div div } \tau = f \text{ in } \Omega}} \int_{\Omega} \mathbf{M}^{-1} \tau : \tau d\mathbf{x} + l \int_{\Omega} \theta(\mathbf{x}) d\mathbf{x} \quad (3.20)$$

and

$$\min_{(\theta, \mathbf{M}) \in \mathcal{A}} J(\theta, \mathbf{M}) = \min_{(\theta, \mathbf{M}) \in \mathcal{A}} \min_{\substack{\tau \in L^2(\Omega; \text{Sym}) \\ \text{div div } \tau = f \text{ in } \Omega}} \int_{\Omega} \mathbf{M}^{-1} \tau : \tau d\mathbf{x} + l \int_{\Omega} \theta(\mathbf{x}) d\mathbf{x}.$$



## Theorem (Necessary conditions of optimality)

If  $(\theta^*, \mathbf{M}^*)$  is a minimizer of the objective function (3.19), and if  $\sigma^*$  is the unique corresponding minimizer in (3.20), then  $\sigma^* = \mathbf{M}^* \nabla \nabla u^*$ , where  $u^*$  is the state function for  $(\theta^*, \mathbf{M}^*)$ . Furthermore,  $\mathbf{M}^*$  satisfies, almost everywhere in  $\Omega$ ,

$$\mathbf{M}^{*-1} \sigma^* : \sigma^* = h(\theta^*, \sigma^*) := \min_{\mathbf{M} \in G_\theta} \mathbf{M}^{-1} \sigma : \sigma, \quad (3.21)$$

where  $h(\theta^*, \sigma^*)$  is the lower Hashin-Shtrikman bound on the complementary energy, while  $\theta^*$  is the unique minimizer of the convex minimization problem

$$\min_{0 \leq \theta \leq 1} (h(\theta, \sigma^*) + l\theta), \quad \text{a.e. on } \Omega. \quad (3.22)$$



## Theorem

For the objective function (3.19) we have

$$\min_{(\theta, \mathbf{M}) \in \mathcal{A}} J(\theta, \mathbf{M}) = \min_{(\theta, \mathbf{M}) \in \mathcal{L}^+} J(\theta, \mathbf{M}),$$

where  $\mathcal{L}^+$  is the set of sequentially laminated designs defined as

$$\mathcal{L}^+ := \left\{ (\theta, \mathbf{M}) \in L^\infty(\Omega; [0, 1] \times \mathfrak{M}_2(\alpha, \beta; \Omega)) : \mathbf{M}(\mathbf{x}) \in L_{\theta(\mathbf{x})}^+, \text{ a.e. in } \Omega \right\},$$

where  $L_\theta^+$ , for  $\theta \in [0, 1]$ , is the set of all sequential laminates  $\mathbf{M}$ , with core  $\mathbf{A}$  and matrix  $\mathbf{B}$ , in proportions  $\theta$  and  $(1 - \theta)$ , respectively. If  $(\theta^*, \mathbf{M}^*)$  is a minimizer of  $J$  in  $\mathcal{A}$ , and if  $\boldsymbol{\sigma}^*$  is its associated stress tensor which minimizes (3.20), then there exists a sequential laminate  $\tilde{\mathbf{M}}$  such that  $(\theta^*, \tilde{\mathbf{M}})$  is a minimizer of  $J$  in  $\mathcal{L}^+$ ,  $\boldsymbol{\sigma}^*$  is again its associated stress tensor, and  $\mathbf{M}^{*-1} \boldsymbol{\sigma}^* = \tilde{\mathbf{M}}^{-1} \boldsymbol{\sigma}^*$ .



## Algorithm

Take some initial  $\theta^0$  and  $\mathbf{M}^0$ . For  $k \geq 0$ :

- 1 Calculate  $u^k$ , the solution of

$$\begin{cases} \operatorname{div} \operatorname{div} (\mathbf{M}^k \nabla \nabla u^k) = f \\ u^k \in H_0^2(\Omega), \end{cases}$$

and define  $\boldsymbol{\sigma}^k := \mathbf{M}^k \nabla \nabla u^k$ .

- 2 For  $\mathbf{x} \in \Omega$ , take  $\theta^{k+1}(\mathbf{x})$  as the zero of the function

$$\theta \mapsto \frac{\partial h}{\partial \theta}(\theta, \boldsymbol{\sigma}^k(\mathbf{x})) + l,$$

and if a zero doesn't exist, take 0 (or 1) if the function is positive (or negative) on  $[0, 1]$ .

- 3 Let  $\mathbf{M}^{k+1}(\mathbf{x})$  be the minimizer in the definition of  $h(\theta^{k+1}(\mathbf{x}), \boldsymbol{\sigma}^k(\mathbf{x}))$ .



*Thank you for your attention!*